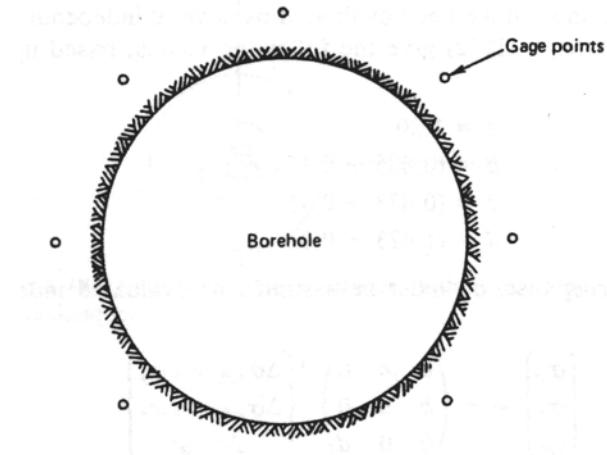
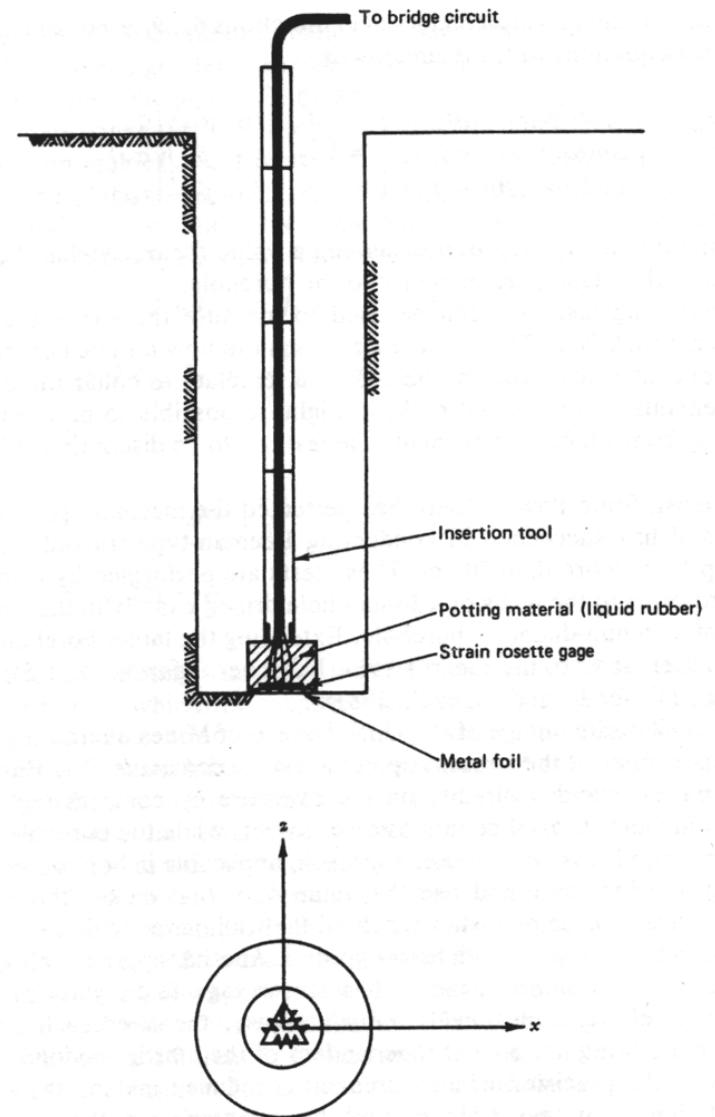
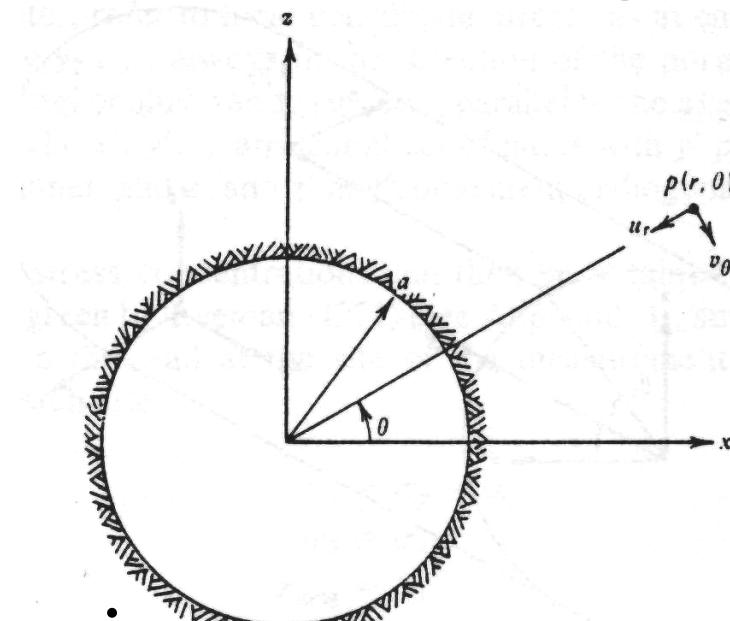


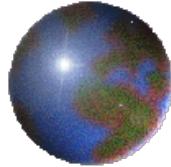
Surface relief (measure displacement or strain)



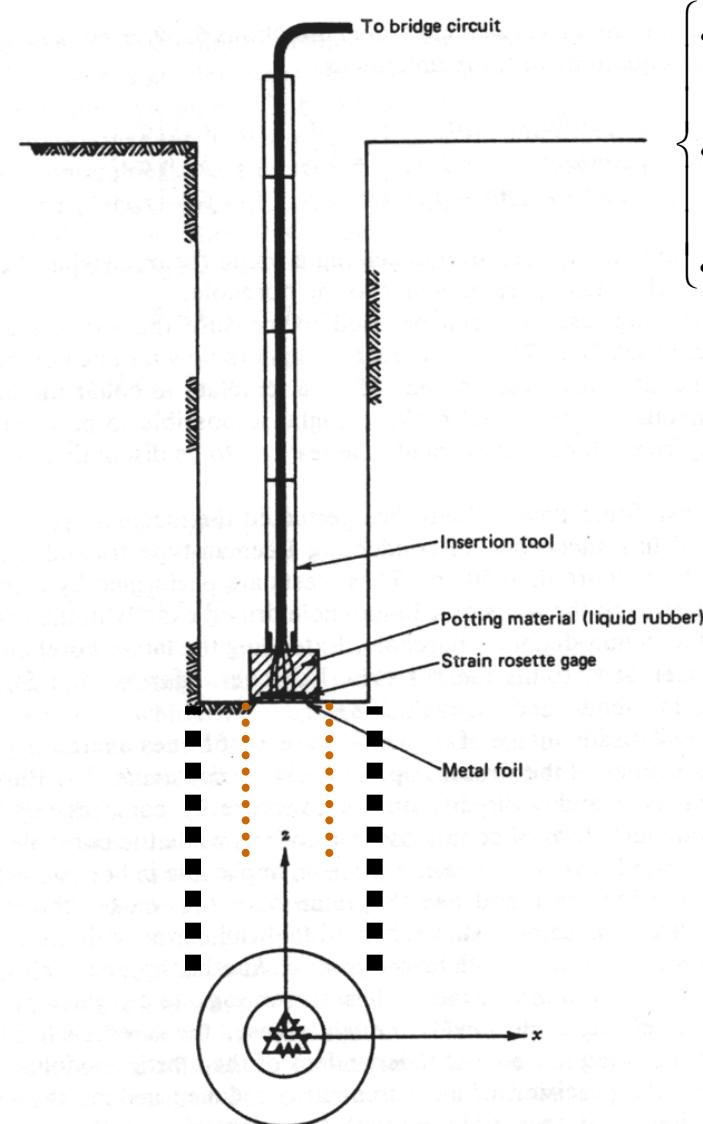
Pin → Undercoring



Doorstopper biaxial strain cell → Overcoring



Surface relief



Doorstopper biaxial strain cell

$$\begin{Bmatrix} \varepsilon_A \\ \varepsilon_B \\ \varepsilon_C \end{Bmatrix} \rightarrow \begin{Bmatrix} \varepsilon_{x'} \\ \varepsilon_{z'} \\ \gamma_{x'z'} \end{Bmatrix}$$

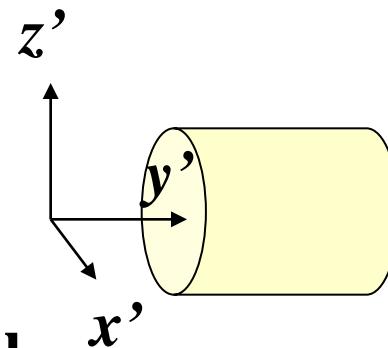
*Strain analysis
(coordinate transformation)*

$$\begin{Bmatrix} \varepsilon_{x'} \\ \varepsilon_{z'} \\ \gamma_{x'z'} \end{Bmatrix} \rightarrow \begin{Bmatrix} \Delta\sigma_{x'} \\ \Delta\sigma_{z'} \\ \Delta\tau_{x'z'} \end{Bmatrix}$$

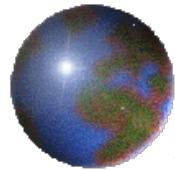
Elastic relation

$$\begin{Bmatrix} \Delta\sigma_{x'} \\ \Delta\sigma_{z'} \\ \Delta\tau_{x'z'} \end{Bmatrix} \rightarrow \begin{Bmatrix} \sigma_{x'} \\ \sigma_{y'} \\ \sigma_{z'} \\ \tau_{y'z'} \end{Bmatrix}$$

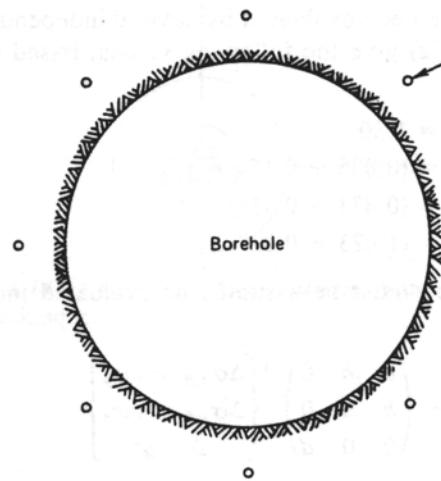
Finite element analysis



At surface, $\sigma_{y'} = 0$



Surface relief

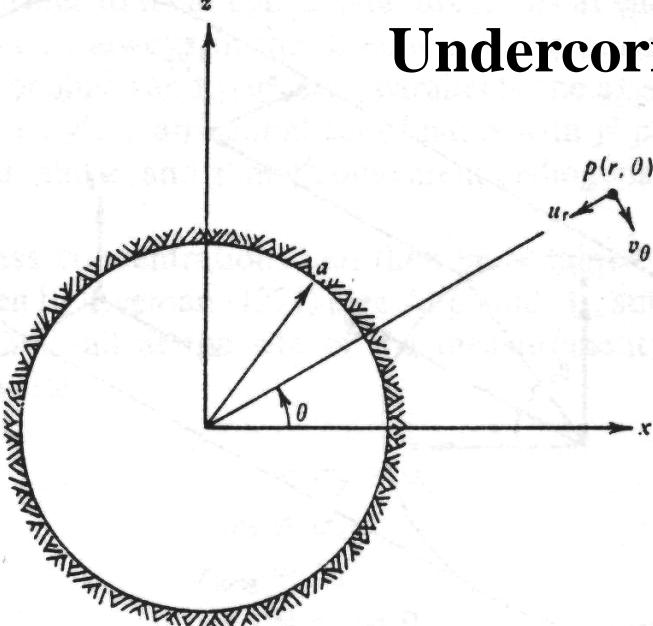


$$u_{r,1} = -\frac{a^2}{2Gr} \left[\frac{\sigma_h + \sigma_v}{2} + \frac{\sigma_h - \sigma_v}{2} \cdot \left\{ 4 \cdot (1-\nu) - \frac{a^2}{r^2} \right\} \cdot \cos 2(\theta + \theta_1) \right]$$

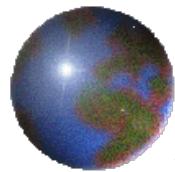
$$u_{r,1} = -\frac{a^2}{2Gr} \left[\frac{\sigma_h + \sigma_v}{2} + \frac{\sigma_h - \sigma_v}{2} \cdot \left\{ 4 \cdot (1-\nu) - \frac{a^2}{r^2} \right\} \cdot \cos 2(\theta + \theta_2) \right]$$

$$u_{r,1} = -\frac{a^2}{2Gr} \left[\frac{\sigma_h + \sigma_v}{2} + \frac{\sigma_h - \sigma_v}{2} \cdot \left\{ 4 \cdot (1-\nu) - \frac{a^2}{r^2} \right\} \cdot \cos 2(\theta + \theta_3) \right]$$

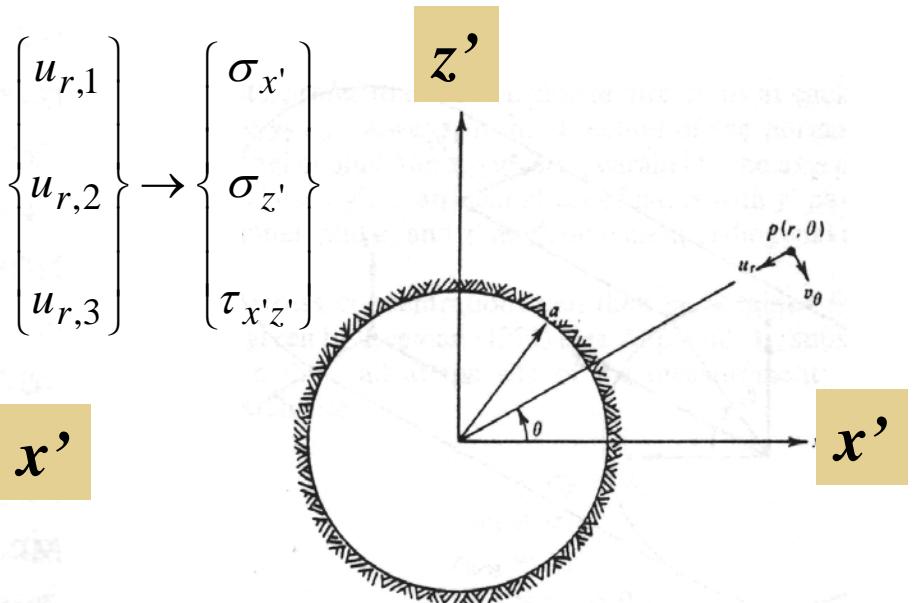
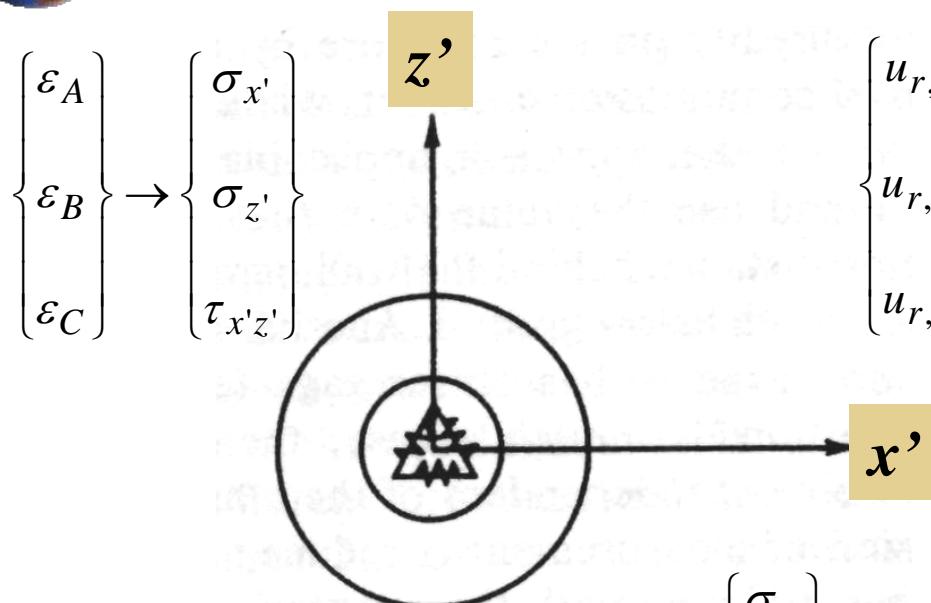
Undercoring



$$\begin{cases} u_{r,1} \\ u_{r,2} \\ u_{r,3} \end{cases} \rightarrow \begin{cases} \sigma_{x'} \\ \sigma_{z'} \\ \tau_{x'z'} \end{cases}$$



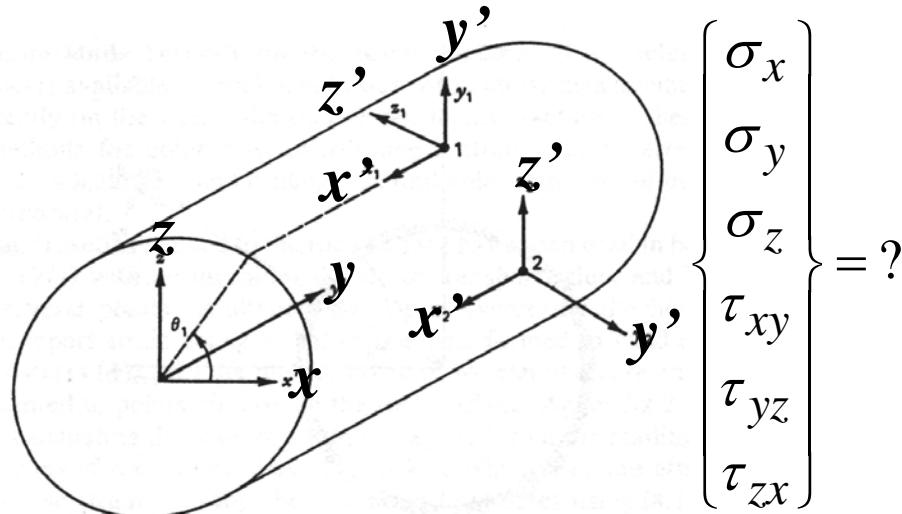
Modification of stress concentration

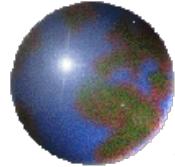


General Kirsch formulas (Leeman, 1971)

$$\begin{pmatrix} \sigma_{x'} \\ \sigma_{z'} \\ \tau_{x'z'} \end{pmatrix} = \begin{pmatrix} d & 0 & e & 0 & 0 & f \\ g & 1 & h & 0 & 0 & i \\ 0 & 0 & 0 & n & p & 0 \end{pmatrix} \begin{pmatrix} \sigma_x \\ \sigma_y \\ \sigma_z \\ \tau_{xy} \\ \tau_{yz} \\ \tau_{zx} \end{pmatrix}$$

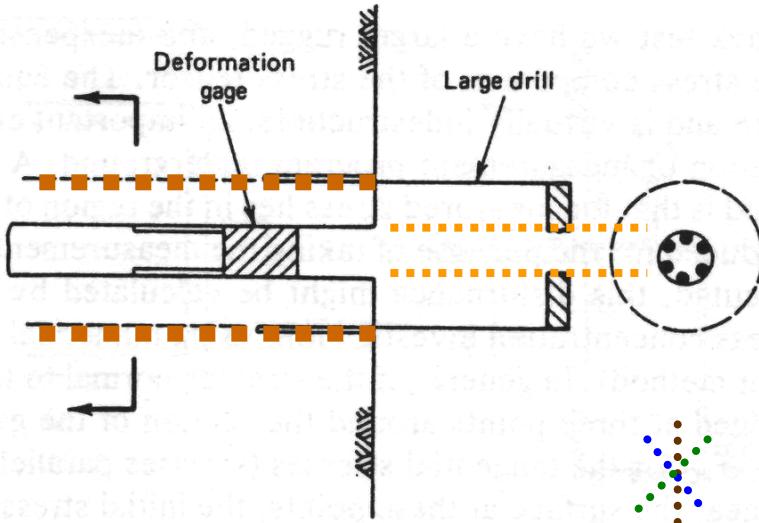
Function of θ



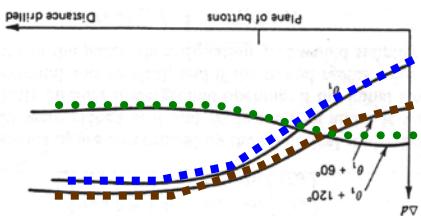


Borehole relief (measure displacement or strain)

$$\Delta d(\theta) = \sigma_{x'} \cdot f_1(\theta) + \sigma_{y'} \cdot f_2(\theta) + \sigma_{z'} \cdot f_3(\theta) + \tau_{x'z'} \cdot f_4(\theta)$$



USBM gage



$\sigma_{y'}$ is assumed

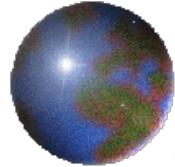
$$f_4(\theta) = d \cdot (4 \sin 2\theta) \frac{1-\nu^2}{E}$$

$$f_1(\theta) = d \cdot (1 + 2 \cos 2\theta) \frac{1-\nu^2}{E} + \frac{d \cdot \nu^2}{E}$$

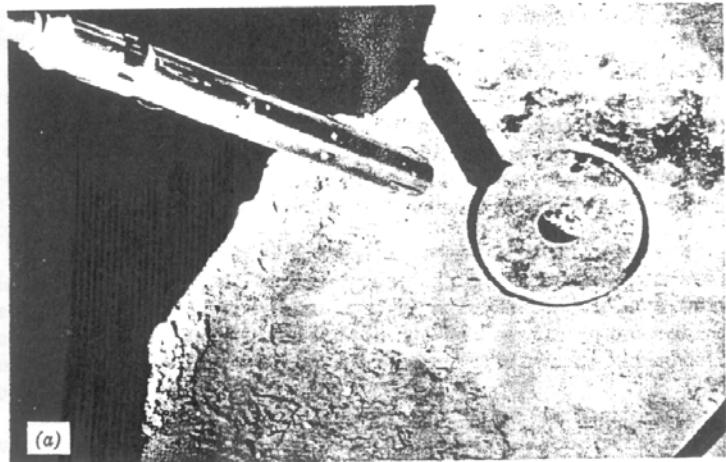
$$f_2(\theta) = -\frac{d \cdot \nu}{E}$$

$$f_3(\theta) = d \cdot (1 - 2 \cos 2\theta) \frac{1-\nu^2}{E} + \frac{d \cdot \nu^2}{E}$$

$\begin{Bmatrix} \sigma_{x'} \\ \sigma_{z'} \\ \tau_{x'z'} \end{Bmatrix}$ can be solved

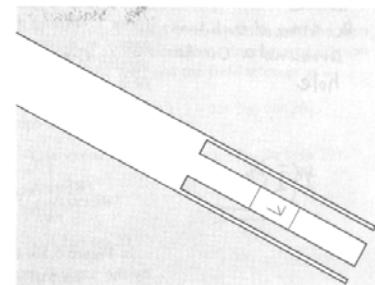
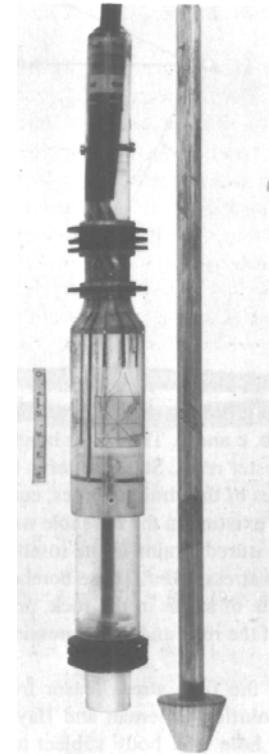
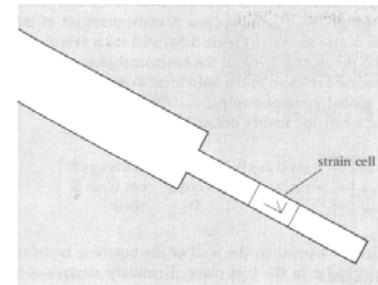
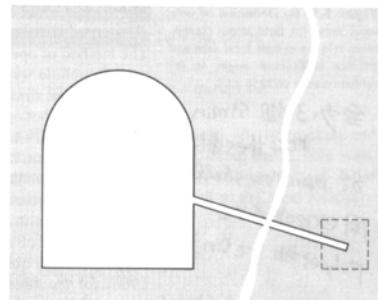
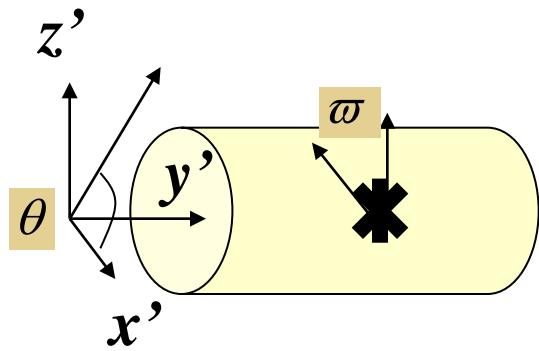


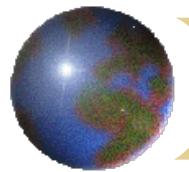
Borehole relief



$$\varepsilon(\theta, \varpi) = A_{xx} \cdot \sigma_{x'} + A_{yy} \cdot \sigma_{y'} + A_{zz} \cdot \sigma_{z'} + \\ A_{xz} \cdot \tau_{x'z'} + A_{xy} \cdot \tau_{x'y'} + A_{yz} \cdot \tau_{y'z'}$$

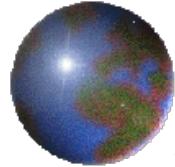
CSIRO triaxial strain cell





HW4

- ➊ Ch 5, problem 2 and problem 3



In-situ stress measurement

- Hydraulic method (**measure stress at failure**)
 - Hydraulic fracture
 - Sleeve fracture
 - Hydraulic test on pre-existing fracture
- Flat jack method (**measure compensate stress**)
- Relief method (**measure displacement or strain**)
 - Surface relief (**pin, Doorstopper biaxial strain cell**)
 - Borehole relief (**USBM gage, CSIRO triaxial strain cell**)

An overview of rock stress measurement method